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Studies in the Generalized Theory of Gravitation II: The Velocity of Light

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STUDIES IN THE GENERALIZED THEORY OF GRAVITATION II:
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1. The various meanings of the velocity of light.

As is well known, the influence of a gravitational field on the propagation of light was in Einstein's theory of gravitation one of the main issues, which by good luck was just within the reach of careful observation, that decided in favour of this theory. In its recent non-symmetric generalization the question arises, how the skew field, which is tentatively regarded as the electromagnetic field, influences the propagation of waves of this very field itself, that is of light, if our tentative view is appropriate. The subject is touched upon in several recent papers¹⁾. Pondering these remarks we found that the first requirement is a revision of the concept "velocity of light" which has two fundamental meanings in the older theory, but three in the new one. We shall discuss both cases briefly, beginning, of course, with the older one.

1)

R. L. Ingraham, *Annals of Math.*, 52, 743, 1950.

P. Udeschini, *Rend. Lincei*, 9, 256, 1950; 10, 21, 121, 390, 1951.

To declare that the symmetric tensor-field g_{ik} is the world metric, implies the physical assumptions that we have unit measuring rods and clocks which measure the invariant interval

$$ds^2 = g_{ik} dx_i dx_k$$

in particular cases, viz. a rod for simultaneous positions of its end-points (irrespective of its orientation), and a clock, when at rest, for the two world points indicated by its having advanced by one unit. - A second and independent physical hypothesis is about the propagation of light: the dx_k for two neighbouring points reached by one light signal shall satisfy $ds^2 = 0$.

If we lay out a local frame with the help of such rods and clocks, choosing rectangular Cartesian space coordinates, the g_{ik} acquire the values $g_{11} = g_{22} = g_{33} = -1$, $g_{44} = 1$, all others zero (we shall call this "Galilean"), and the velocity of light becomes 1 in all directions; all this in virtue of our assumptions, which would have to be discarded if experience contradicted. Needless to say that in this local frame there can be no question of rods or clocks changing, contracting or being retarded, etc., by the gravitational field or by orientation, etc.

In an extended gravitational field one can always adopt a general world frame of which this local frame at a given world-point forms part, and usually, with sufficient accuracy, in a wide neighbourhood (it may be a geodesic frame, but that is not the point; the one we use every day is not),

This is the first meaning of the velocity of light in the

older theory. It is the only invariant meaning, although - nay, because - it refers to a very special frame. However the very nature of a true gravitational field makes it impossible to choose a world-frame that produces this simple state of affairs everywhere. We cannot avoid using a general frame for studying extended phenomena such as the deflection of light passing near the limb of the sun, or the wavelength of a spectral ray, emitted on a white dwarf and measured in a terrestrial observatory. One can as a rule - and does, of course, if one can - avoid $g_{i4} \neq 0$ ($i = 1, 2, 3$). This leads to

$$ds^2 = g_{44} dx_4^2 - \sum_{i=1}^3 \sum_{k=1}^3 g_{ik} dx_i dx_k .$$

This induces one to interpret a $g_{44} \neq 1$ as a change of rate of the clock, and non-Galilean spatial g_{ik} 's as a change of length of the rod, depending also on its orientation, and finally to say that the velocity of light is $\neq 1$ and is "anisotropic". But it is quite clear that all these notions are eminently non-invariant and locally meaningless, since they disappear in the local frame. In fact you may, if you are provoked, produce all kinds of freak by choosing a suitably unsuitable frame !

This, then, is the second, the non-invariant concept of the velocity of light. That it is sometimes needed for predicting very definite and substantial phenomena, is well known.

In the way of a digression I should like to repudiate a third meaning, used by Udeschini l. c. and hailing, it seems,

from Levi-Civita, viz. to regard $\sqrt{g_{44}}$ as the velocity of light. The idea is, to regard in the above equation the double sum as the square of the distance, say dr^2 , and dx_4 as the time interval so that $ds^2 = 0$ entails $\frac{dr}{dx_4} = \pm \sqrt{g_{44}}$. The physicist has no use for this concept. It combines the defects of being non-invariant and yet producing wrong results for the gravitational deviation of a light ray. -

We now turn to the generalized theory in which g_{ik} is non-symmetric. To regard its even part $\underline{g_{ik}}$ as the world-metric amounts to hold on to the assumptions about clocks and measuring rods, now with regard to the invariant

$$ds^2 = \underline{g_{ik}} dx_i dx_k.$$

In the local frame the $\underline{g_{ik}}$ will then turn out Galilean, as the g_{ik} did before. But what about the propagation of light? It consists of waves of $\underline{g_{ik}}$, and the latter are controlled by the field equations just as much as the $\underline{g_{ik}}$. So there is now no room for an assumption as $ds^2 = 0$ or any other. If we wish to know how such waves are propagated we have to consult the field equations. These stipulate an intimate interaction between the $\underline{g_{ik}}$ - and $\underline{g_{ik}}$ -fields. Hence, with a rapidly changing $\underline{g_{ik}}$ -field the $\underline{g_{ik}}$ could in general not remain Galilean for more than a split second!

It is, however, reasonable to define the "behaviour of light" in the following manner. We split the total skew $\underline{g_{ik}}$ field additively into two parts: an infinitely weak, rapidly oscillating part that represents the light-wave whose behaviour we wish to investigate, and the remaining background-field, which we do not restrict as to its magnitude but which we

consider to vary slowly in space and time, so that we may regard it as constant in the neighbourhood of the point in question just as we do with the Galilean g_{ik} , whose distortion by the infinitely weak rapidly changing light wave we neglect. In this way we shall find

i) with the g_{ik} Galilean and no background- g_{ik} the propagation of light is normal, $ds^2 = 0$, the velocity of light being constant and $= 1$.

ii) With the g_{ik} Galilean and a background- g_{ik} , the latter modifies the propagation of light, owing to the non-linearity of the equations controlling g_{ik} . This behaviour may still be called local and invariant inasmuch as it is only an interplay of local fields and undergoes surveyable changes on Lorentz transformation.

iii) In a general world-frame the background- g_{ik} , by acting as a source of the gravitational field g_{ik} , has also indirect, non-local, non-specific influence on the non-invariant behaviour of light in such a frame; very generally speaking this influence is of the same type as in the older theory and raises no new problems.

These are the three meanings of the "velocity of light" in the new theory. The feature of specific interest is, of course, (ii), comprising (i) as a special case. We deal with it in the next section.

2. The influence of the local background-field.

It is easy to show¹⁾ that the density μ^{ik} and the tensor g_{ik} are, if you allow for the generalized metric g_{ik} , in the same relation to each other as the 2 six-vectors in Born's non-linear electrodynamics; μ^{ik} is to be identified with the (B,E)-tensor, the g_{ik} with the (H,D)-tensor. Then the relation $\mu^{ik}_{,k} = 0$ - the only Maxwellian set that the unified theory yields²⁾ - corresponds to $\text{curl } \mathbf{E} + \dot{\mathbf{B}} = 0$, $\text{div } \mathbf{B} = 0$, while the other set is obtained by defining $g_{[ik,1]}$ as the 4-current and putting it zero where there is to be none. This yields $\text{curl } \mathbf{H} - \dot{\mathbf{D}} = 0$, $\text{div } \mathbf{D} = 0$ (generalized for the metric g_{ik}). Hence the local velocity of light (the only one that has an invariant meaning), since it is obtained by introducing a local Galilean frame $(-1, -1, -1, 1)$, is governed precisely by Born's theory, and we can make use of results worked out previously.

We shall use the letters B, E, D, H for a field of arbitrary strength (the background field), that we think of as

1) E. Schrödinger, Proc. Roy. Ir. Acad. 51 (A), p. 214, 1948.

In equation (5,6a) the factor h is missing in the second term of the 2nd member.

2) Equation (4,8b) l.c. and the suggestion (5,7) become void in the more stringent form of the theory, which we are using here. - Also, in the present connection, being interested in local phenomena, we discard the cosmological term altogether.

locally homogeneous and static or, at any rate, as varying slowly in space and time compared with the vibrations of the light-fields whose propagation we are about to investigate (but for which no notation will be required). In the case of a purely electric field E (and the corresponding D , see below) it has been found³⁾, that the velocity of propagation u in the direction of the wave normal of a weak plane wave crossing the background field is, irrespective of polarization and frequency, given by

$$u^2 = A^2 \sin^2 \omega + \cos^2 \omega, \quad (1)$$

where ω is the angle between the wave-normal and E . Thus the field E produces anisotropy, but no double refraction, and it does not upset the central symmetry ($\omega \rightarrow \pi - \omega$). The scalar A , which we regard as positive, is

$$A = \sqrt{1 - E^2}. \quad (2)$$

Its reciprocal plays the part of dielectric constant for the background-field

$$D = A^{-1} E. \quad (3)$$

It is not difficult to generalize the argument N. O. l. c. so as to embrace the case of parallel fields E and H . The only change is that then

$$A = \sqrt{1 - E^2 - H^2} \quad (2a)$$

while (3) is supplemented by⁴⁾

3)

E. Schrödinger, Non-linear Optics, Proc. Roy. Ir. Acad.

47(A), p. 101 f. (This paper shall be quoted as N. O.)

4) N. O. p. 81, equations (2,6)

(8)

$$B = A^{-1} H. \quad (3a)$$

To obtain the general case when E and H are not necessarily parallel, the simplest way is to put (1), without changing its content, into Lorentz-invariant form. We first express A^2 by the invariants of the (B,E)-tensor. From (2a) and (3a)

$$A^2 = 1 - E^2 - A^2 B^2$$

$$A^2 = \frac{1 - E^2}{1 + B^2} = \frac{2 - E^2 + B^2}{1 + B^2} - 1 = 1 - \frac{E^2 + B^2}{1 + B^2} \quad (4)$$

$$\frac{1 - A^2}{1 + A^2} = \frac{E^2 + B^2}{2 + B^2 - E^2} = \frac{I}{1 + I_1},$$

where we have put

$$I_1 = \frac{1}{2}(B^2 - E^2) \quad I_2 = (BE) = \pm |B| |E| \quad (5)$$

$$I = \sqrt{I_1^2 + I_2^2}.$$

From the last equation (4)

$$A^2 = \frac{1 + I_1 - I}{1 + I_1 + I}. \quad (6)$$

Now we divide (1) by the square of the wavelength^{*} λ , in order to introduce the covariant wave vector k_1, k_2, k_3, k_4 , the latter being u/λ , while k_2 shall be the component in the direction

*

One could avoid specializing in harmonic waves; but by doing so no harm is done and language is simplified.

of the background field ($\omega = 0$). Thus, from (1):

$$k_4^2 = A^2 (k_1^2 + k_3^2) + k_2^2, \quad (7)$$

Inserting the value of A^2 from (6) we easily obtain

$$(1 + I_1)(k_4^2 - k_1^2 - k_2^2 - k_3^2) = -I (k_1^2 + k_3^2 + k_4^2) + I k_2^2 \quad (8).$$

It remains to put the second member into invariant form.

Using transitorily the contravariant components k^1 :

$$(1 + I_1)k^1 k_1 = I k^1 k_1 - I k^2 k_2 + I k^3 k_3 - I k^4 k_4. \quad (8a)$$

We now introduce, as a purely mathematical tool the conventional Maxwellian energy-momentum-stress tensor of the tensor (B,E), and call it \overline{T}_m^1 . It is easy to see that in our special frame, with both B and E parallel to the direction labelled 2, T_m^1 is diagonal with components

$$-I, \quad I, \quad -I, \quad I.$$

Hence the invariant form of (8a) reads

$$(1 + I_1) k^1 k_1 = -T_m^1 k^m k_1, \quad (8b)$$

and must, of course, hold in every frame; which means inter alia for any field (B,E). Given this field, we shall still try to use the most convenient frame. We cannot without loss of generality make T diagonal, because there will be a "Poynting-vector" unless B and E are parallel. But we can reduce that P. V. to one component (say in the 1-direction) and take for "2" and "3" the other two axes of the (threedimensional)

(10)

"stress-tensor". It is not difficult to see that T_m^1 is then the following array

$$\begin{pmatrix} -w & 0 & 0 & +\sqrt{w^2 - I^2} \\ 0 & I & 0 & 0 \\ 0 & 0 & -I & 0 \\ -\sqrt{w^2 - I^2} & 0 & 0 & w \end{pmatrix} \quad (9)$$

The letter w has been chosen for the "energy density". This we introduce in (8b), which at the same time we multiply by the square of the wave-length and thus replace the (covariant) k_l by

$$-\cos\Theta, \quad -\sin\Theta\cos\phi, \quad -\sin\Theta\sin\phi, \quad u.$$

So Θ is the angle between the wave normal and the "Poynting-vector", ϕ is the azimuth around the latter direction. Taking good care of the signs we get in this way from (8b) and (9)

$$(1 + I_1)(u^2 - 1) = 2u \cos\Theta \sqrt{w^2 - I^2} - w \cos^2\Theta + I \sin^2\Theta \cos 2\phi - w u^2$$

or

$$u^2 - 2u \cos\Theta \frac{\sqrt{w^2 - I^2}}{1 + I_1 + w} + \frac{w \cos^2\Theta - I \sin^2\Theta \cos 2\phi - I_1 - 1}{1 + I_1 + w} = 0. \quad (10)$$

This quadratic equation gives u , the velocity of propagation of the wave plane in the direction of the wave normal indicated

by the angles Θ, ϕ . The most striking feature is the term linear in u , which is bound up with the non-vanishing "Poynting-vector". It means that the centre of symmetry is lost; u has in general different values for opposite directions $(\phi, \Theta) \rightarrow (\phi + \pi, \pi - \Theta)$. Apart from extreme cases (see below) the two roots have opposite signs; the negative root, with reversed sign, gives u for the opposite direction. The easiest way of procuring a synoptic view of the rather intricate state of affairs is to construct the eikonal - the envelope, after unit time, of all the wave planes that have passed the origin simultaneously in all possible directions. We skip the proof that this eikonal is an ellipsoid in standard orientation, but with its centre displaced in the 1-direction. Taking this for granted we easily find the half-axes and the displacement by computing u in the directions of the coordinates. In this way one obtains for the half-axes

$$\begin{array}{ccc}
 (1) & (2) & (3) \\
 \frac{\sqrt{1 + 2I_1 - I_2^2}}{1 + I_1 + w} & \sqrt{\frac{1 + I_1 + I}{1 + I_1 + w}} & \sqrt{\frac{1 + I_1 - I}{1 + I_1 + w}} \quad (11)
 \end{array}$$

and for the displacement of the centre in the direction of the "Poynting-vector" (+1-direction)

$$+ \frac{\sqrt{w^2 - I^2}}{1 + I_1 + w} \quad (12)$$

In general the three half-axes are different. Rotational symmetry around the 2-axis occurs for $w = I$; this is the

(12)

special case of B and E parallel, from which we started;
 $u = 1$ for the ± 2 -directions. The ellipsoid is "prolonged".
The displacement is zero. - A flattened ellipsoid of rotation around the 1-axis is obtained when both invariants vanish: $I_1 = I_2 = I = 0$. The displacement (12) subsists in this case, and cannot be transformed away. The velocity u in the direction of the "Poynting-vector" is unchanged

$$u = \frac{1}{1 + w} + \frac{w}{1 + w} = 1.$$

It is the case of E and B orthogonal and equal, and from (6) also equal to D and H. It is almost a gift from heaven, due obviously to continuity, that this singular case is embraced, though it seems out of reach of the considerations that led to equation (10).

Since a plane wave proceeding with the maximum velocity $u = 1$ does so in every Lorentz frame, there must also in the general case be just two directions in which (but not in the opposites!) $u = 1$. (For $B \parallel E$ these are the directions ± 2 ; in the singular case they happen to coincide in the direction $+ 1$), Obviously we have to seek them in the (1,2)-plane, i. e. for $\phi = 0$ or π . So we have $\cos 2\phi = 1$ in equation (10), which we write

$$(1 + I_1 + w) u^2 - 2u \cos \Theta \sqrt{w^2 - I^2} + (w + I) \cos^2 \Theta - I - I_1 - 1 = 0 \quad (13)$$

To determine, when u as a function of $\cos \Theta$ has a maximum,

we might write out the differential of the first member for increments du , $d\cos\Theta$, and then put their quotient = 0. But that amounts to putting the factor of $d\cos\Theta$ equal to zero. Thus the maxima are determined by

$$-2u \sqrt{w^2 - I^2} + 2(w + I) \cos\Theta = 0.$$

We have the legitimate presumption that the maximum values of u are 1; hence

$$\cos\Theta = \pm \sqrt{\frac{w - I}{w + I}} \quad (14)$$

gives the two directions, symmetrical with respect to the $+1$ -direction. It is easy to check that (13) actually has the root $u = 1$ for this value of $\cos\Theta$. The extreme cases mentioned before are correctly encompassed by $w = I$ and $I = 0$, respectively. -

It is hardly necessary to point out that all these deviations from normal behaviour, i. e. from $u = 1$, are presumably minute, since the unities in which our fields B , E , etc. are measured are presumably extremely outsized. Even so, the consequences of non-linearity have some interest by principle. Easily the quaintest event is, that in an extremely outsized background field the displacement (12) can become bigger than the 1-half-axis of the ellipsoid, which then excludes the origin, so that within a certain cone of wave-normals no positive u is available, and wave fronts cannot proceed in those directions. The condition for this freak to occur is, from (12) and (11),

(14)

$$\sqrt{w^2 - I^2} \geq \sqrt{1 + 2I_1 - I_2^2}$$

$$\text{or } w^2 \geq 1 + 2I_1 - I_2^2 + I^2 = (1 + I_1)^2$$

$$w \geq 1 + I_1$$

$$\text{or } \frac{1}{2}(B^2 + E^2) \geq 1 + \frac{1}{2}(B^2 - E^2)$$

$$\text{or } E^2 \geq 1. \quad (15)$$

But can that be? - Well, the only irrefragable requirement in Born's electrodynamics is

$$A^2 = \frac{1 + I_1 - I}{1 + I_1 + I} = \frac{(1 + I_1)^2 - I^2}{(1 + I_1 + I)^2} \geq 0.$$

Thus

$$(1 + I_1)^2 - I^2 = 1 + 2I_1 - I_2^2 \geq 0$$

or

$$1 + B^2 - E^2 - (BE)^2 \geq 0$$

or

$$E^2 \leq \frac{1 + B^2}{1 + B^2 \cos^2 \alpha}, \quad (16)$$

where α is the angle between B and E . Hence E^2 is well allowed to surpass 1, provided that $B^2 \neq 0$ and $\cos^2 \alpha \neq 1$.

One might be inclined to brush aside this freak (as I called it) because it requires field strengths that cannot ever be reached. Far from this, given any non-vanishing (E, B) -field

whatsoever, you can, in a suitable Lorentz frame, make E^2 surpass unity. This is almost self-evident, since the independent invariants are

$$\frac{1}{2}(B^2 - E^2), \quad (BE).$$

Thus $|B|$ and $|E|$ may be increased indefinitely, in step with each other, provided that $\cos\alpha$ approaches to zero, so as to keep also the second invariant invariant.